

LECTURE NO 15 &16

Gradient of a scalar function

Del operator is given by $\nabla = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z}$

$$\nabla \phi = \left(\frac{\partial \phi}{\partial x} \mathbf{i} + \frac{\partial \phi}{\partial y} \mathbf{j} + \frac{\partial \phi}{\partial z} \mathbf{k} \right)$$

$$\text{grad } \phi = \nabla \phi = \mathbf{i} \frac{\partial \phi}{\partial x} + \mathbf{j} \frac{\partial \phi}{\partial y} + \mathbf{k} \frac{\partial \phi}{\partial z}$$

$$\mathbf{k} \frac{\partial \phi}{\partial z} = \mathbf{i} \frac{\partial \phi}{\partial x} + \mathbf{j} \frac{\partial \phi}{\partial y} + \mathbf{k} \frac{\partial \phi}{\partial z}$$

$$\frac{\partial \phi}{\partial y} \mathbf{j} + \mathbf{k} \frac{\partial \phi}{\partial z}$$

$$\text{grad } \phi = \nabla \phi = \mathbf{i} \frac{\partial \phi}{\partial x} + \mathbf{j} \frac{\partial \phi}{\partial y} + \mathbf{k} \frac{\partial \phi}{\partial z}$$

Div (Divergence of a vector function)

If $\mathbf{A} = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}$, then

$$\text{div } \mathbf{A} = \nabla \cdot \mathbf{A} = \left(\mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z} \right) \cdot (a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k})$$

$$\text{div } \mathbf{A} = \nabla \cdot \mathbf{A} = \frac{\partial a_1}{\partial x} + \frac{\partial a_2}{\partial y} + \frac{\partial a_3}{\partial z}$$

Note that

- (a) the grad operator acts on a scalar and gives a vector
- (b) the div operator acts on a vector and gives a scalar.

Example 4: If $\mathbf{A} = x^2 y \mathbf{i} + x y z \mathbf{j} + y z^2 \mathbf{k}$, then find Div \mathbf{A} .

Solution:

$$\text{Div } \mathbf{A} = \nabla \cdot \mathbf{A} = \frac{\partial}{\partial x}(x^2y) + \frac{\partial}{\partial y}(xyz) + \frac{\partial}{\partial z}(yz^2) = 2xy + xz + 2yz$$

Example 5: If $\mathbf{A} = 2x^2y\mathbf{i} - 2(xy^2 + y^3z)\mathbf{j} + 3y^2z^2\mathbf{k}$, determine $\nabla \cdot \mathbf{A}$ i.e. $\text{div } \mathbf{A}$. **Solution:** $\mathbf{A} = 2x^2y\mathbf{i} - 2(xy^2 + y^3z)\mathbf{j} + 3y^2z^2\mathbf{k}$

$$\nabla \cdot \mathbf{A} = \frac{\partial}{\partial x}a_x + \frac{\partial}{\partial y}a_y + \frac{\partial}{\partial z}a_z = 4xy - 2(2xy + 3y^2z) + 6y^2z = 4xy - 4xy - 6y^2z + 6y^2z = 0$$

Such a vector \mathbf{A} for which $\nabla \cdot \mathbf{A} = 0$ at all points, i.e. for all values of x, y, z , is called a solenoid vector. It is rather a special case.

Curl (Curl of a Vector Function)

The curl operator denoted by $\nabla \times$, acts on a vector and gives another vector as a result. If $\mathbf{A} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$ then $\text{curl } \mathbf{A} = \nabla \times \mathbf{A}$.

$$\text{i.e. } \text{curl } \mathbf{A} = \nabla \times \mathbf{A} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_1 & a_2 & a_3 \end{vmatrix} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_1 & a_2 & a_3 \end{vmatrix}$$

$$= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_1 & a_2 & a_3 \end{vmatrix} = \mathbf{i} \left(\frac{\partial a_3}{\partial y} - \frac{\partial a_2}{\partial z} \right) + \mathbf{j} \left(\frac{\partial a_1}{\partial z} - \frac{\partial a_3}{\partial x} \right) + \mathbf{k} \left(\frac{\partial a_2}{\partial x} - \frac{\partial a_1}{\partial y} \right)$$

$\text{Curl } \mathbf{A}$ is thus a vector function.

Stokes' Theorem

In words we can state Stokes' theorem as the line integral of the tangential component of a vector function \vec{A} taken around a simple closed curve C is equal to the surface integral of the normal component of the curl of \vec{A} taken over any surface S having C as its boundary.

Statement

It states that if S is an open, two sided surface bounded by a simple closed curve C, then if \vec{A} has continuous first partial derivatives

$$\oint_C \vec{A} \cdot d\vec{r} = \iint_S (\nabla \times \vec{A}) \cdot \hat{n} dS$$

Where C is traversed in the positive direction.

Proof

If \vec{A} is expressed as $\vec{A} = A_1\hat{i} + A_2\hat{j} + A_3\hat{k}$, then the divergence theorem can be written as

$$\iint_S \nabla \times (A_1\hat{i} + A_2\hat{j} + A_3\hat{k}) dS = \oint_C A_1 dx + A_2 dy + A_3 dz$$

We will prove this theorem for a surface S which has the property that its projection on the xy, yz and zx planes are regions bounded by simple closed curves as shown in figure.